#### **AFRL-VA-WP-TP-2004-314**

AUTOMATED AERIAL REFUEL (AAR)
TECHNOLOGIES AND
CHALLENGES
Delivery Order 0048

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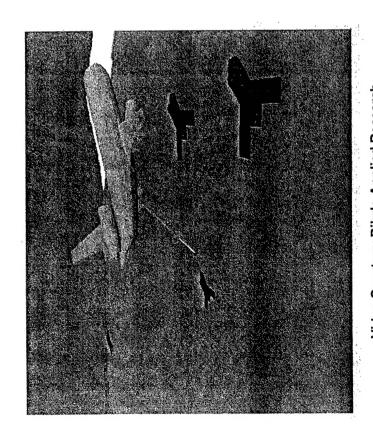
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# **Automated Aerial Refuel (AAR) Technologies and Challenges**

#### AIAA Section Meeting 13 Apr 04



Video Courtesy Bihrle Applied Research



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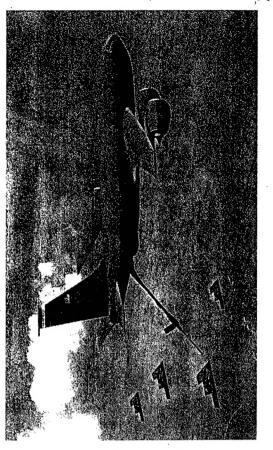




# **Presentation Outline**



- Background
- Significance to Air Force
- AAR Program Key Aspects
- AAR Project Approach
- National AAR Team
- Conceptual Design Development Process
- AAR Process
- CONOPs and Requirements
- Conceptual Designs
- Selection Process
- Conceptual Design Families
- Simulation Development
- AAR's Future





# Significance to Air Force

- Unmanned Aerial Vehicles
- Extends Range
- Shortens Response for Time-Critical Targets
- Maintains In-Theater Presence Using Fewer Assets
- Deployment with Manned Fighters and Attack Without the Need of Forward Staging Areas



"If we decided to fly them across the ocean, we have to work on things like automatic air refueling" -Gen. John Jumper, USAF, August

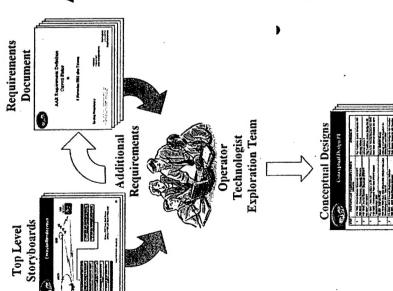
### Manned Aircraft

- Provides Adverse Weather Operations
- Improves Fueling Efficiency
- Reduces Pilot Workload





# **AAR Program Key Aspects**



Automating the Receiver

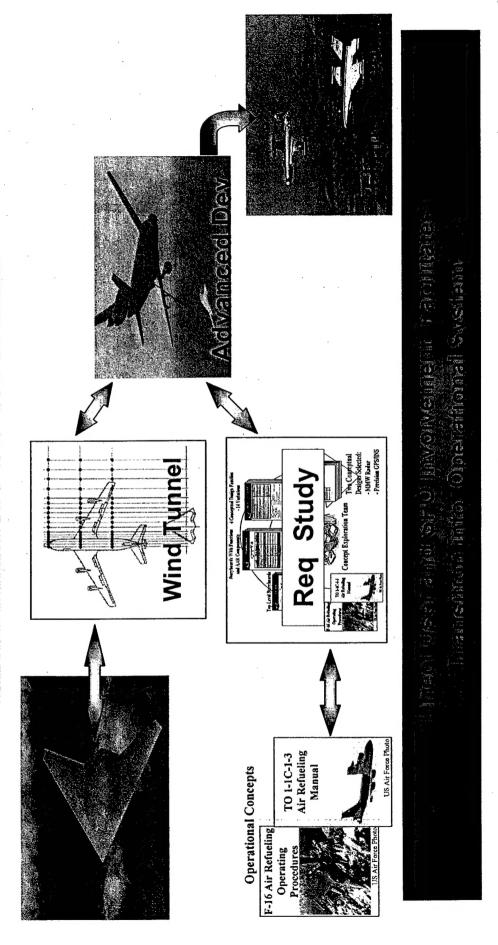
- Demonstrate an Operationally Feasible UAV Refueling Capability
- Near-Term Focus Boom/Receptacle Refueling
- Target was Air Force UAVs
- Near-Term Refueling

TOUR SOLD ON THE WASHINGTON



# **AAR Project Approach**

Heavy User Involvement From AMC/XPR, ACC/DRZ, ASC/FB, And DARPA





# National AAR Team



ACC/DR



ASC/FB ASC/GR



**AMC/XP** 



Navy





Electronic Systems

NORTHROP GRUMMAN

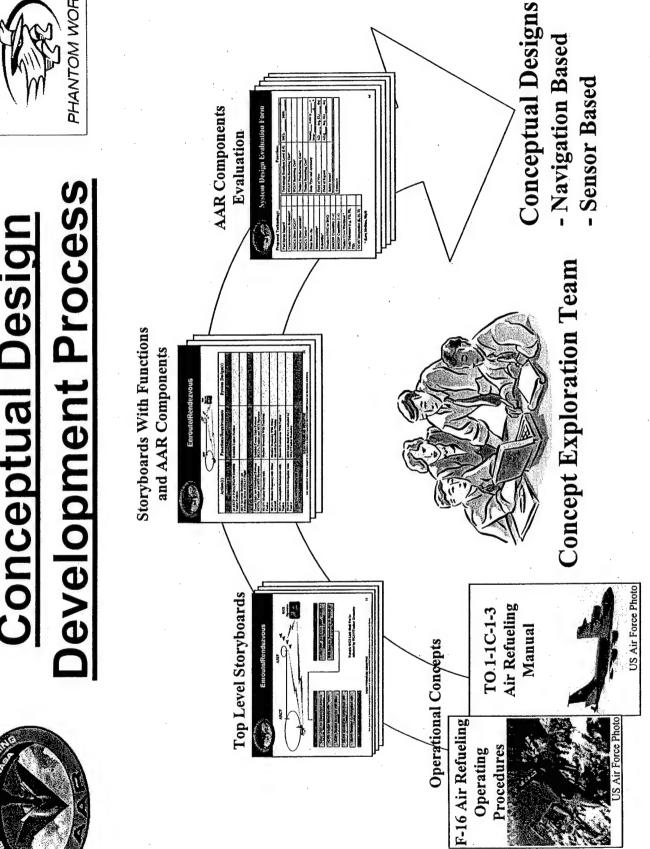






# Conceptual Design







# J-UCAS Mission/AAR

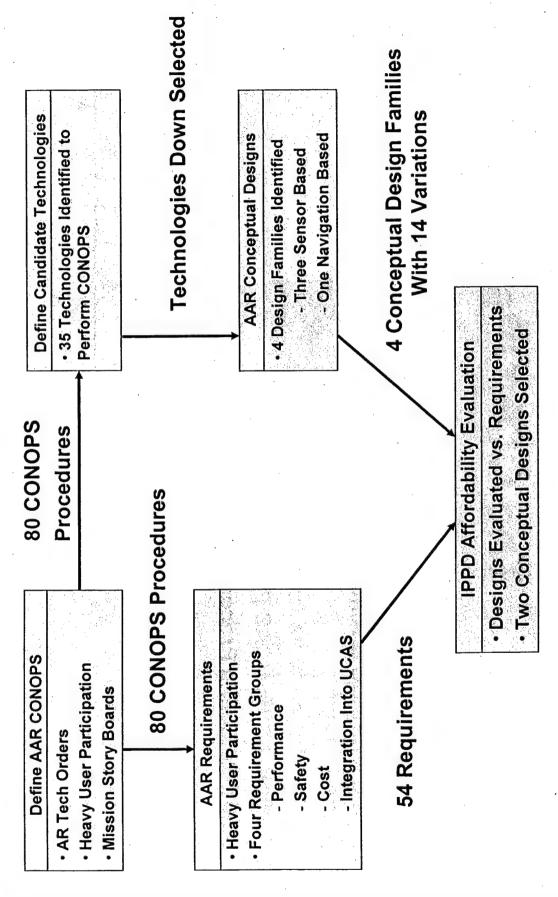






# The AAR Process



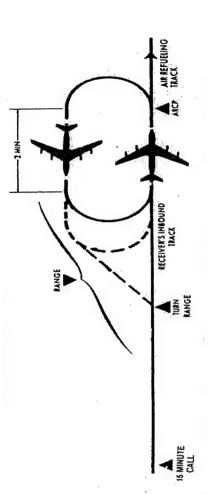




## The CONOPs

- Working with ACC & AMC to Develop Conops
- Used F-16 Procedures As Baseline
- Refueling 4-Ship UCAS Packages
- Manned Refueling Procedures



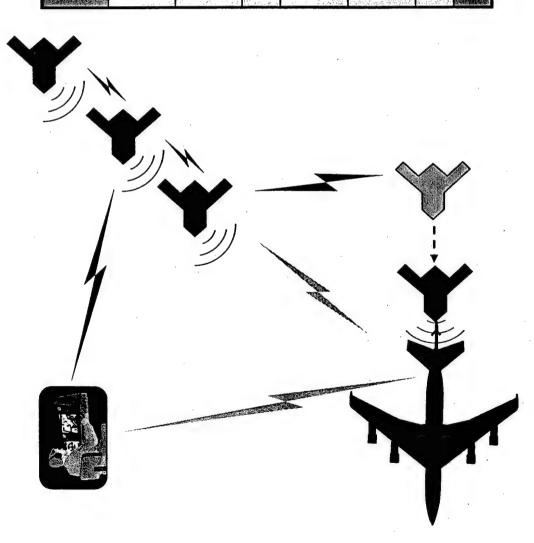


Based AAR Procedures On Current Manned Aircraft Procedure ट्राज्यातीगर् डेंश्वालीड्ड जिएंश्वर्तातीला, हिंबड्ड निकाणडांधिका



### Example CONOPs: Contact Position





## Authorized UGAS Stabilizes in Pre-Confact Position

Boomer Authorizes UCAS to Contact Position

Authorized UCAS Stabilizes in Contact Position

**Boomer Plugs UCAS** 

UCAS Acknowledges Contact to MCS Operator

Confirmation of Contact Is Provided to Tanker UCAS Maintains Contact Position

UCAS Takes Fuel



### Overarching User Requirements



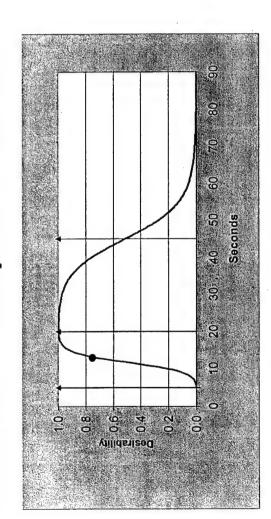
- User Relevance Requires:
- **Protect Tanker From Collision With UCASs**
- Identify and Design Most Affordable Solution
- Consider Impact to Rest of UCAS System of Systems (SoS) Impact
- Minimal Impact to LO Design
- · Minimize (or Eliminate) Tanker Modifications
- Minimize Impact to Refueling Mixed Fleet Operation



## AAR Requirements: Performance Example

POOTE: Refueling Efficiency: Closure to Contact

 UCAV will move smoothly and efficiently from the Precontact Position to the Contact Position upon Boomer authorization.



Time (seconds) from Boomer authorization (to close to contact) until receiver stabilizes in Contact Position. Threshold is the typical time for piloted aircraft.

- 4 Areas
   PerformanceSafetyCost
- 54 Requirements

-Integration

- Developed With Direct Warfighter Involvement
- Derived from Battlefield Requirements and CONOPs



# Conceptual Design Selection Critical Functions Drive AAR

- Strongest Design Drivers Functions (In Order of Priority):
- **UCAS Ability to Precisely Maneuver Around Tanker**
- **UCAS Ability to Perform Rendezvous with Tanker**
- Other Important Functions
- **Boomer Ability to Immediately Command Break-Away**
- Tanker's Ability to Determine Range to UCAS in Real **Fime (Point Parallel Rendezvous)**
- Tanker's Ability to Communicate with MCS Operator

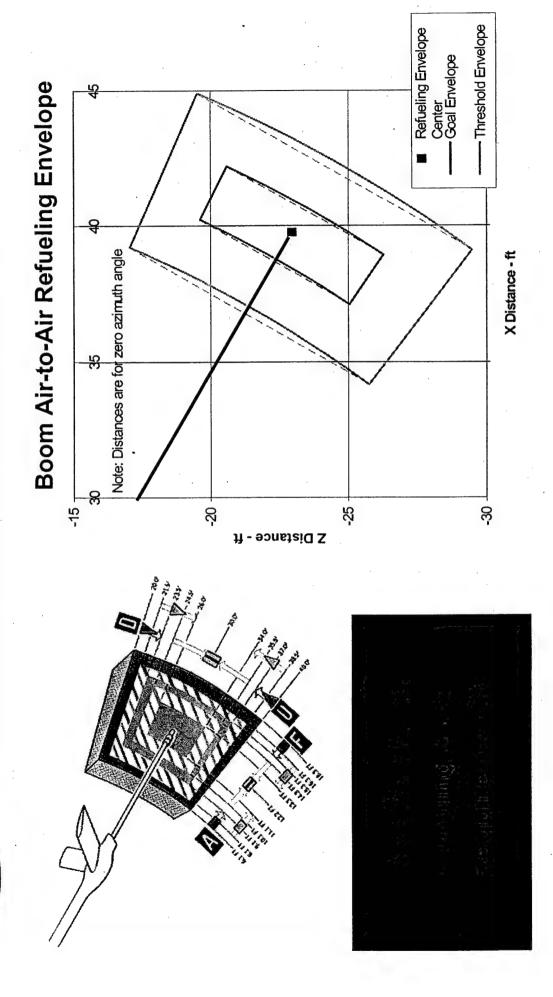






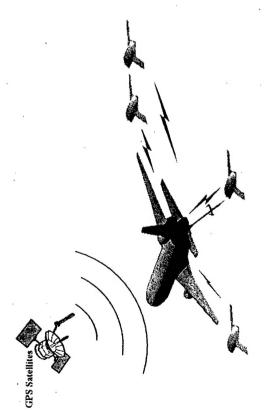








# **AAR Conceptual Design Families**



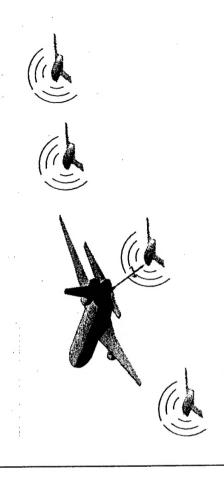
### Navigation-Based

### Advantages:

- Lowest Technical Risk For Initial Capability
- All Weather Capability
- Compatible With Navy Ops
  - Simple Vehicle Integration

### Disadvantages:

Requires Tanker Modifications



### Sensor Based

#### Advantages:

- Most Affordable Conceptual Design
- Sensor May Enable Additional UCAS Capabilities

### Disadvantages:

- **UCAS Vehicle Integration**
- Sensor Development Risk



# Simulation Development

- Integrated Aerial Refueling R&D Simulation Being Developed
- ➤ Boomer Station
- ∨ UCAS Operator Station
- ▼ Tanker Pilot Cube
- Provides Test Bed for AAR System Development
- Allows Rapid Prototyping and Early Operator Interactions
- Helps Develop and Visualize Correct Story Boards



Infinity Cube Simulation

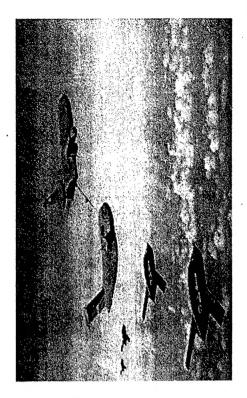




### Summary



- Automated Refueling Is a Key Capability for UCAS
- Automation Can Provide Significant Improvements in Refueling Capability and Efficiency
- **Technology Application to Manned Aircraft**
- Situational Awareness and Collision Avoidance for Simultaneous Multiple Receivers
- AFRL, ASC, AMC, ACC, and DARPA have Teamed With Industry
- Concepts Developed in Desktop Simulation Environment can be Quickly Moved to a Man-In-The-Loop Simulation Environment for Boomer, Tanker Pilot, and UAV Controller Evaluations





## **AAR's Future**



- **Continue Requirements Development**
- Analysis
- Simulation
- Off-Line Simulations
- Real Time "Boomer in the Loop"
- **AAR Technology Maturation**
- Flight Test
- Gather Sensor Data
- Demonstrate Station Keeping Capability
- Demonstrate Dry/Wet Hookups
- ▼ Boom and Receptacle
- **∀** Probe and Drogue

